

Systems and Signals 344

2026

Lecture 7

Variance and Standard Deviation

Section 3.8

Recap

Expected Value

The **expected value** of a **discrete** random variable X is

$$E[X] = \mu_X = \sum_{x \in S_X} x P_X(x)$$

Recap

Functions of a Random Variable

Steps:

1. Perform experiment and observe an outcome $\mathbf{s}$.
2. From $\mathbf{s}$, find $\mathbf{x}$, the corresponding value of random variable $\mathbf{X}$.
3. Observe $\mathbf{y}$ by calculating $\mathbf{y} = g(\mathbf{x})$.
4. For all possible values of $\mathbf{x} \in \mathcal{S}_X$ we compute $\mathbf{y} = g(\mathbf{x})$ to get $\mathcal{S}_Y$.

For a discrete random variable $\mathbf{X}$, the PMF of $\mathbf{Y} = g(\mathbf{X})$ is

$$P_Y(y) = \sum_{x:g(x)=y} P_X(x)$$

Expected Value of a Derived Random Variable

If $Y = g(X)$, $E[Y]$ can be calculated from $P_X(x)$ and $g(X)$ without deriving $P_Y(y)$.

Given a random variable X with PMF $P_X(x)$ and the derived random variable $Y = g(X)$, the expected value of Y is

$$E[Y] = \mu_Y = E[g(X)] = \sum_{x \in S_X} g(x)P_X(x)$$

(note that only the part in front of $P_X(x)$ changed)

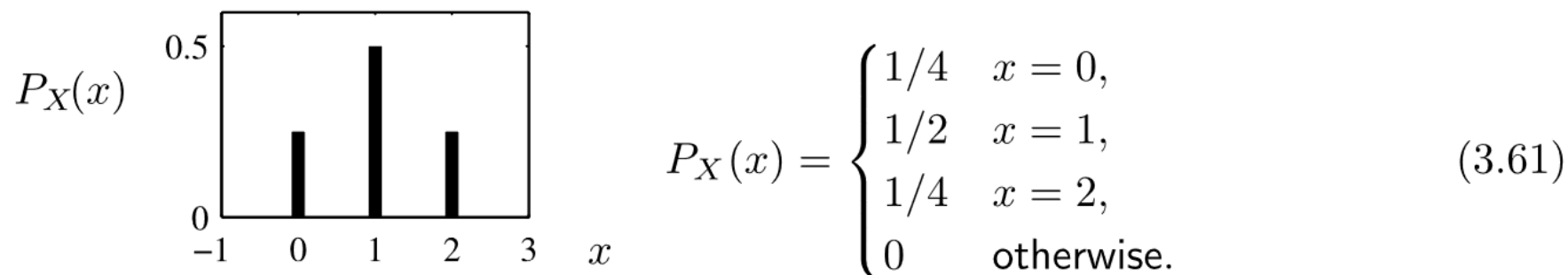
Properties of Expected Values

For any random variable X

- $E[aX + b] = aE[X] + b$
 - This is often called a **linear** transformation. But if $b \neq 0$ then it should technically be called **affine** since the origin is not fixed.
- $E[X - \mu_X] = 0$
- Usually, $E[g(X)] \neq g(E[X])$

Example 3.23

Recall from Examples 3.5 and 3.18 that X has PMF



What is the expected value of $V = g(X) = 4X + 7$?

.....

From Theorem 3.12,

$$\mathbb{E}[V] = \mathbb{E}[g(X)] = \mathbb{E}[4X + 7] = 4\mathbb{E}[X] + 7 = 4(1) + 7 = 11. \quad (3.62)$$

We can verify this result by applying Theorem 3.10:

$$\begin{aligned} \mathbb{E}[V] &= g(0)P_X(0) + g(1)P_X(1) + g(2)P_X(2) \\ &= 7(1/4) + 11(1/2) + 15(1/4) = 11. \end{aligned} \quad (3.63)$$

Variance and Standard Deviation

*The variance $\text{Var}[X]$ measures the *dispersion* (or spread) of sample values of X around the expected value $\text{E}[X]$.*

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$$\text{Var}[X] = \text{E}[(X - \mu_X)^2]$$

It is important to note that $\text{Var}[X]$ does not have the same units as X and can therefore not be drawn on the same graphical axes.

Variance and Standard Deviation

Variance

$$\text{Var}[X] = \text{E}[(X - \mu_X)^2]$$

$$\text{Var}[X] = \text{E}[X^2] - (\text{E}[X])^2$$

$$\text{Var}[X] = \text{E}[X^2] - \mu_X^2$$

Variance and Standard Deviation

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If X has for example units of m , then variance has units of m^2 .
So we can't compare variance with the $\text{E}[X]$...

Variance and Standard Deviation

Variance

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$$\text{Var}[X] = \text{E}[X^2] - (\text{E}[X])^2$$

$$\text{Var}[X] = \text{E}[X^2] - \mu_X^2$$

$$\text{Var}[X] = \sigma_X^2$$

Standard Deviation

$$\sigma_X = \sqrt{\text{Var}[X]}$$

Variance and Standard Deviation

Standard Deviation

$$\sigma_X = \sqrt{\text{Var}[X]}$$

- This is quite useful since σ_X has the same units as X .
- Therefore, the standard deviation can be compared with the expected value.
- For a Gaussian random variable, approximately **68.3%** of the probability lies in $[\mu_X - \sigma_X, \mu_X + \sigma_X]$. No fixed proportion applies to every distribution.

Variance and Standard Deviation

- In many applications we try to make a prediction $\hat{x}$ before performing an experiment and observing a sample value of X (therefore often called the **blind estimate** of X).
- We want to minimise the squared prediction error, and one of the most common criteria used to determine $\hat{x}$ is the **mean squared error (MSE)**:

$$e = \mathbf{E}[(X - \hat{x})^2]$$

In the absence of observations, the minimum mean square error estimate of random variable X is:

$$\hat{x} = \mathbf{E}[X] = \mu_X$$

Variance and Standard Deviation

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$$\hat{x} = \mathbf{E}[X] = \mu_X$$

$$e = \mathbf{E}[(X - \hat{x})^2] = \mathbf{E}[(X - \mu_X)^2] = \text{Var}[X]$$

Properties of Variance and Standard Deviation

- Since $(X - \mu_X)^2 \geq 0$ then $\text{Var}[X] \geq 0$
- $\text{Var}[aX + b] = a^2 \text{Var}[X]$
 - Note that b falls away, since shifting a random variable by a constant does not change the dispersion of outcomes around the expected value.
 - For $a = 0$ then $\text{Var}[b] = 0$ since there is no dispersion around the expected value of a constant.
- Since $\text{Var}[aX] = a^2 \text{Var}[X]$ then $\sigma_{aX} = |a|\sigma_X$

Moments

The **moments** of X summarise aspects of its distribution, but they do not always fully describes the distribution. However, the *moment generating function* does fully describe the distribution.

Moments are quantitative measures related to the shape of a function's graph.

The n^{th} **moment about the origin** of X is, $g_n(x) = x^n$

$$m_n = \mathbf{E}[X^n] = \sum_{x \in S_X} x^n P_X(x)$$

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The n^{th} **central moment** of X is, $g_n(x) = (x - \mu_X)^n$

$$\mu_n = \mathbf{E}[(X - \mu_X)^n] = \sum_{x \in S_X} (x - \mu_X)^n P_X(x)$$

(not to be confused with the expected value μ_X)

This is also sometimes referred to as the **moment about the mean**

Moments

Moment about the origin

1. $m_1 = \mathbb{E}[X] = \mu_X$

2. $m_2 = \mathbb{E}[X^2]$

Central moments

0. $\mu_0 = \mathbb{E}[(X - \mu_X)^0] = 1$

1. $\mu_1 = \mathbb{E}[(X - \mu_X)^1] = 0$

2. $\mu_2 = \mathbb{E}[(X - \mu_X)^2] = \text{Var}[X] = \sigma_X^2$

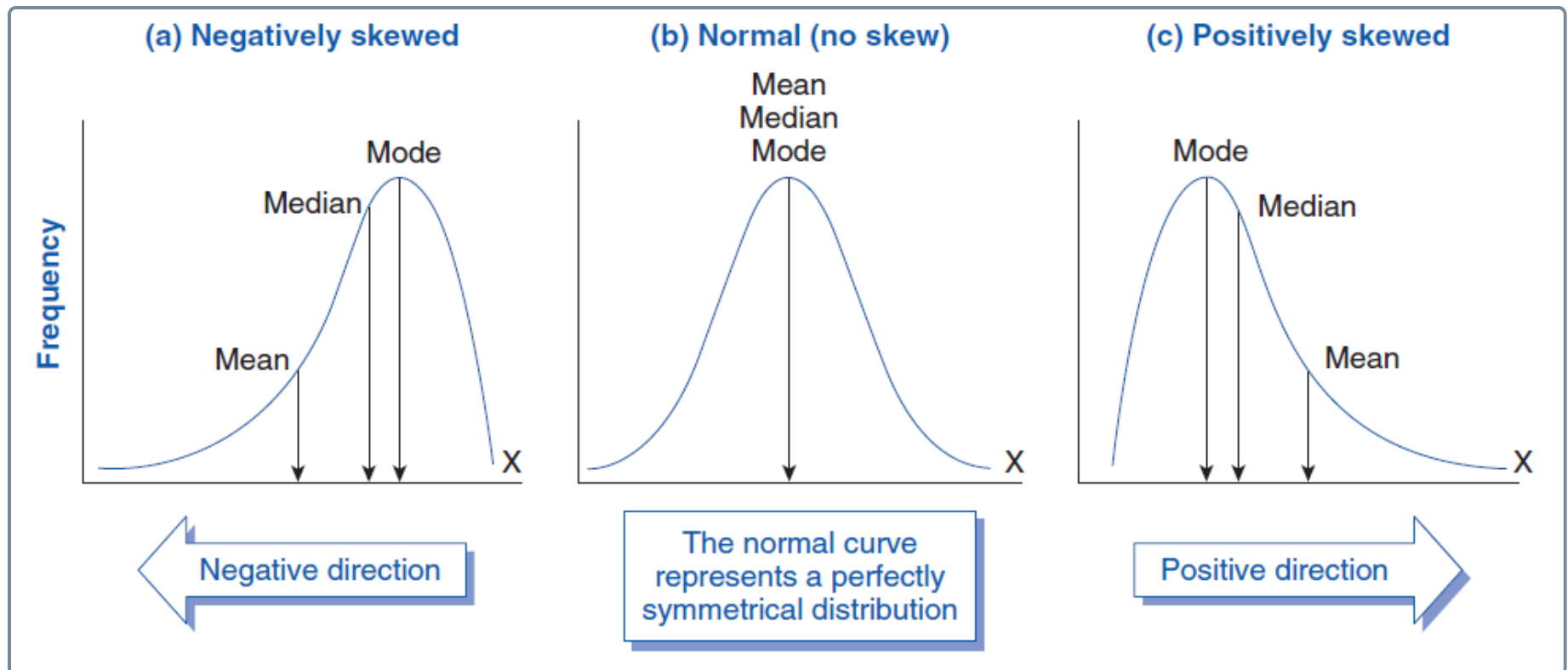
3. $\mu_3 = \mathbb{E}[(X - \mu_X)^3]$ is called **Skew**

- Indicates *asymmetry* about the mean
- Often expressed as **coefficient of skewness** $\gamma = \mu_3/\sigma^3$

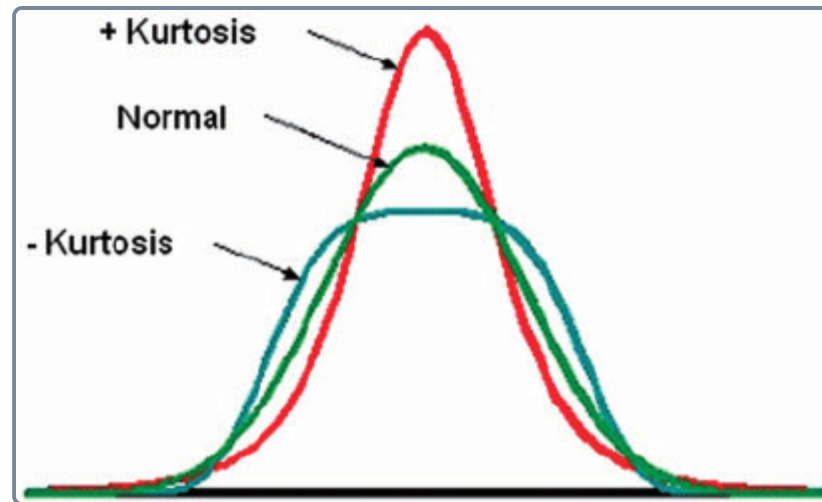
4. $\mu_4 = \mathbb{E}[(X - \mu_X)^4]$ is called **Kurtosis**

- Is a measure of *tailedness*
- Usually normalised $\kappa = \mu_4/\sigma^4$

$\gamma = \frac{E[(X - \mu_X)^3]}{\sigma_X^3}$ is the **coefficient of skewness**

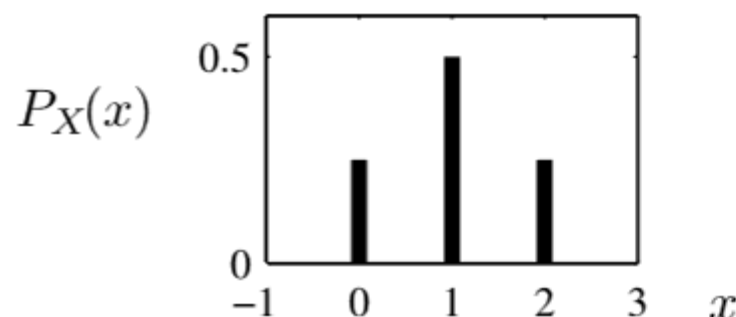


$$\kappa = \frac{\mathbb{E}[(X - \mu_X)^4]}{\sigma_X^4}$$
 is the **kurtosis**



Example 3.25

Continuing Examples 3.5, 3.18, and 3.23, we recall that X has PMF

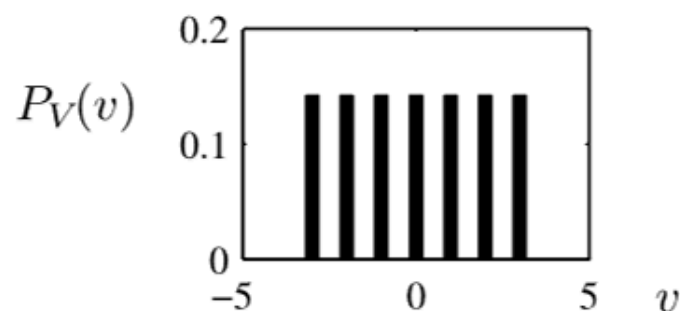


$$P_X(x) = \begin{cases} 1/4 & x = 0, \\ 1/2 & x = 1, \\ 1/4 & x = 2, \\ 0 & \text{otherwise,} \end{cases}$$

and expected value $E[X] = 1$. What is the variance of X ?

Example 3.27

The amplitude V (volts) of a sinusoidal signal is a random variable with PMF



$$P_V(v) = \begin{cases} 1/7 & v = -3, -2, \dots, 3, \\ 0 & \text{otherwise.} \end{cases}$$

A new voltmeter records the amplitude U in millivolts. Find the variance and standard deviation of U .